

# Reconstructing Interventional C-Arm CT Rawdata from Non-Conventional Scan Trajectories

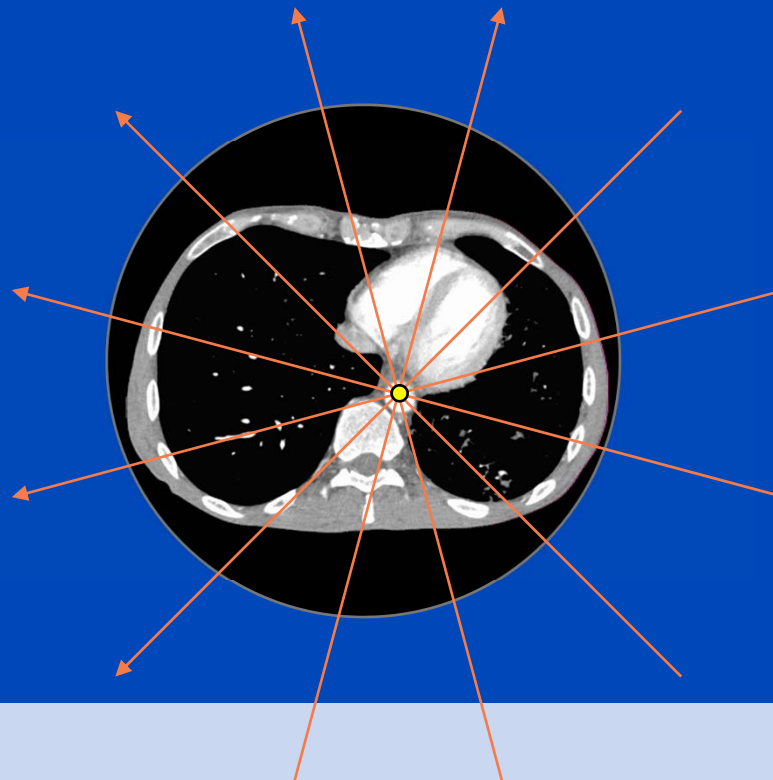
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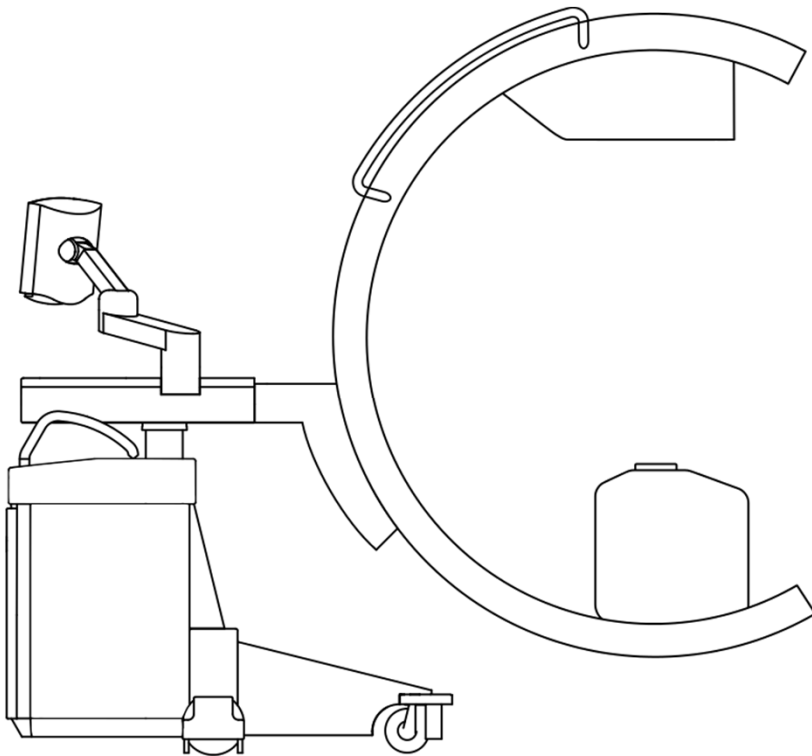
# CT Completeness Condition

- Each voxel has to be acquired from at least  $180^\circ$  to allow for image reconstruction.
- Completeness condition leads to a rotation range of  $180^\circ + \text{fan angle}$  in circular trajectories

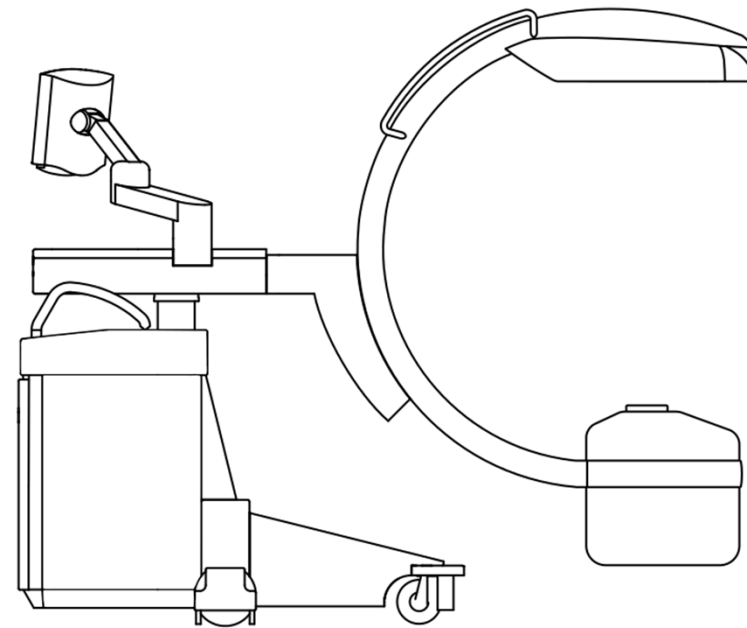


# C-Arm System Design

Rotation range:  $\sim 200^\circ$

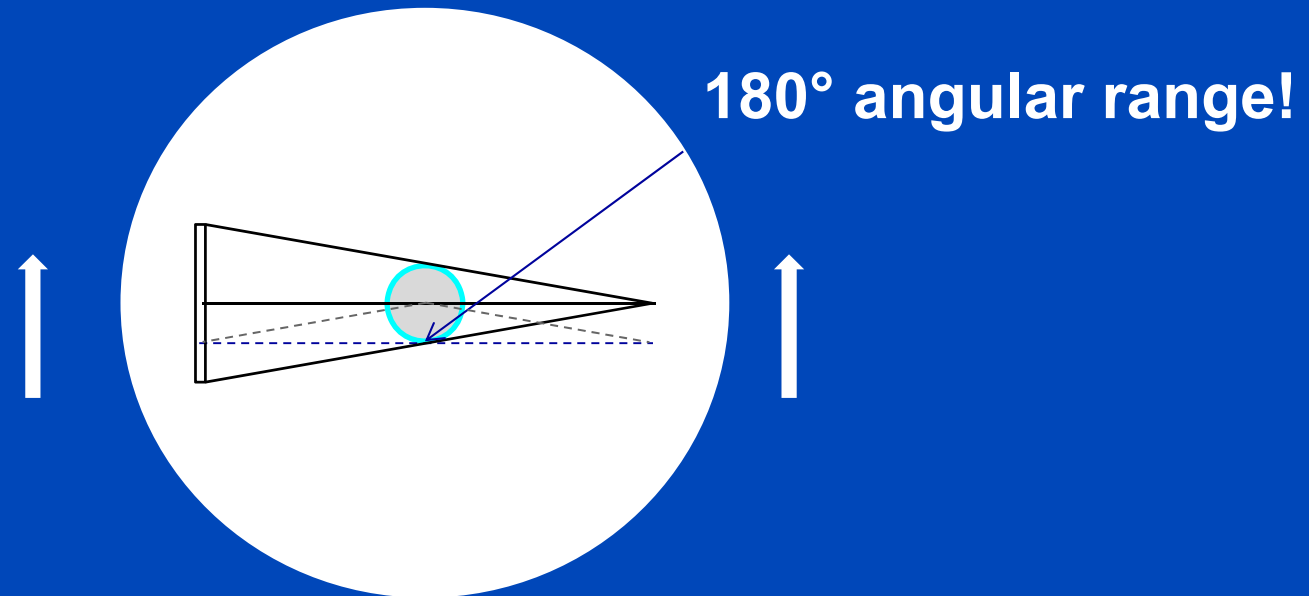


Rotation range:  $\sim 165^\circ$



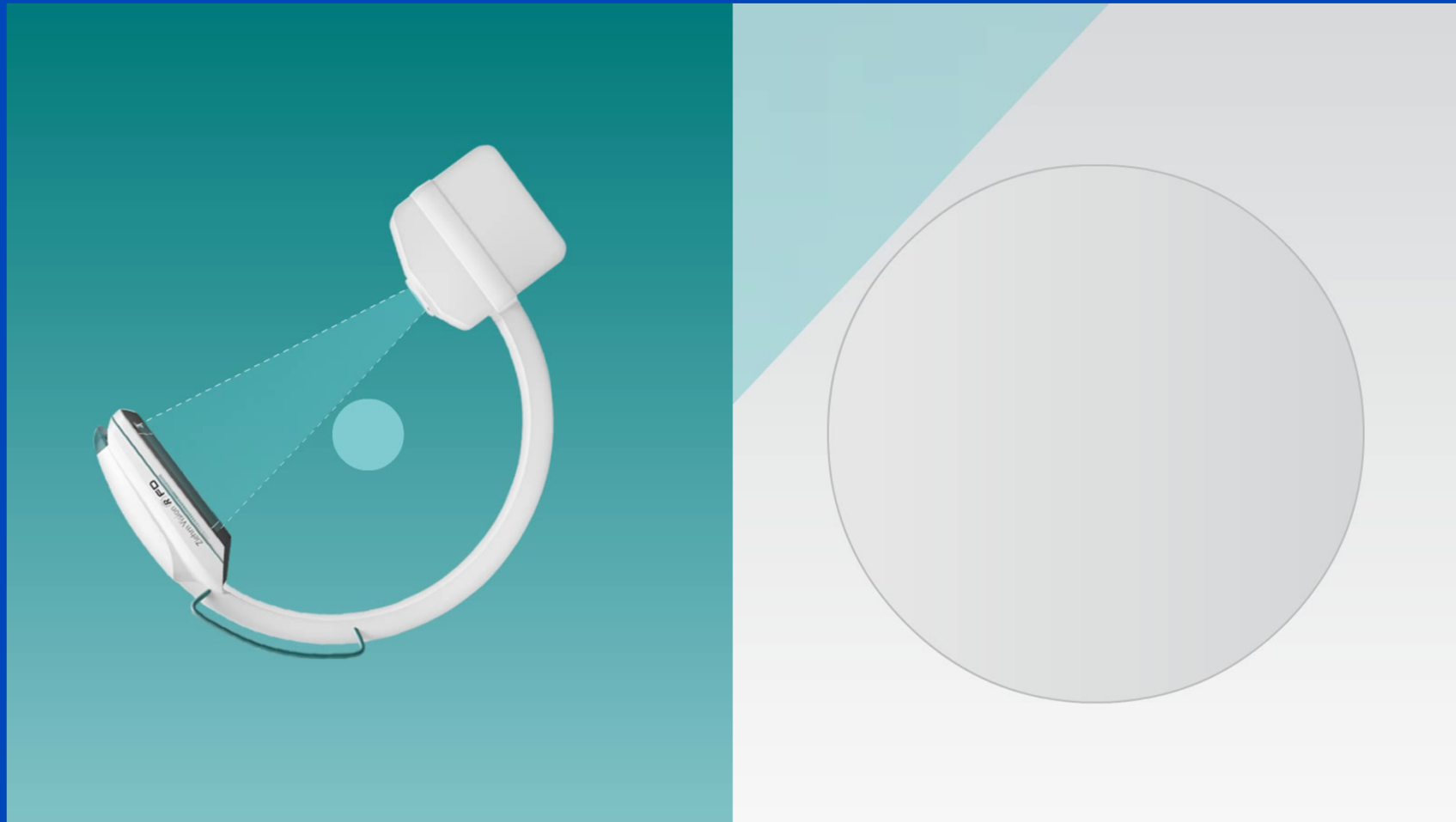
# Data Acquisition

- Rotation range:  $165^\circ$
- Fan angle:  $15^\circ$



**Rotate-plus-shift trajectory: Shifting the beam over the FOV increases the angular range by up to the fan angle  $\varphi$ .**

# Rotate-Plus-Shift Trajectory

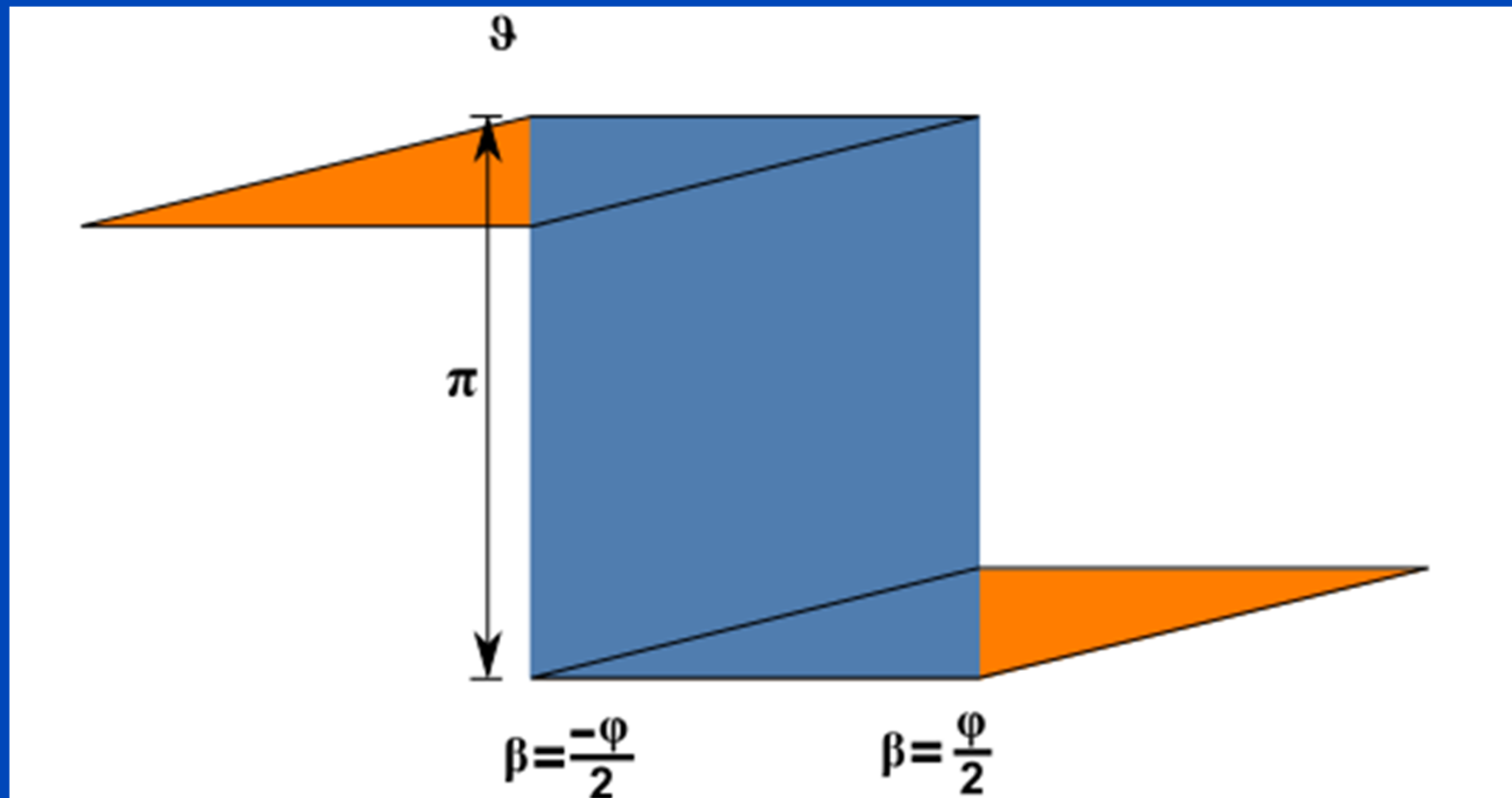


# Rotate-Plus-Shift Scan

- Projection rawdata shown with fixed isocenter

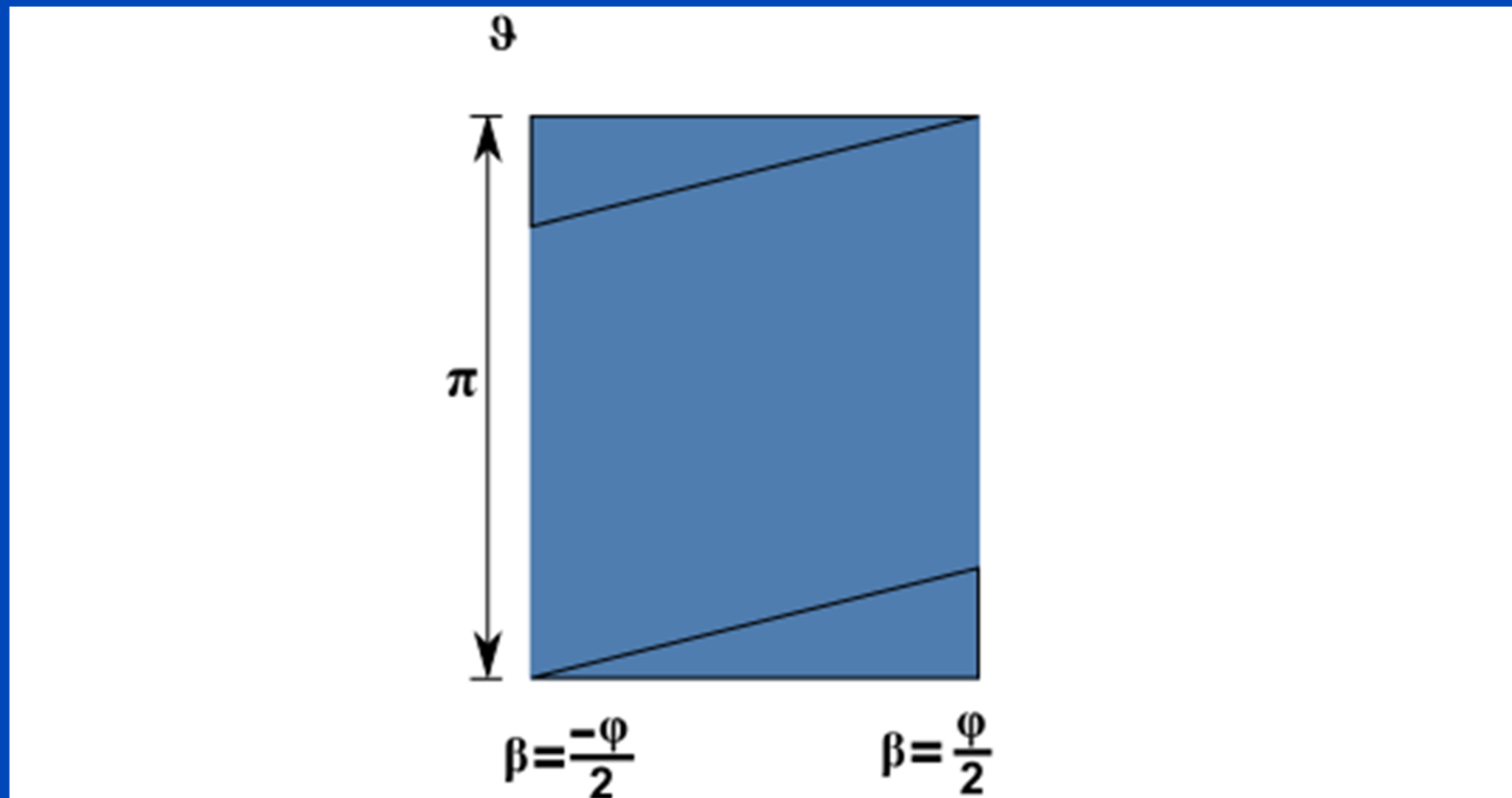
# Rotate-Plus-Shift Trajectory

- Rotate-(180° minus fan angle)-plus-shift sinogram



# Rotate-Plus-Shift Trajectory

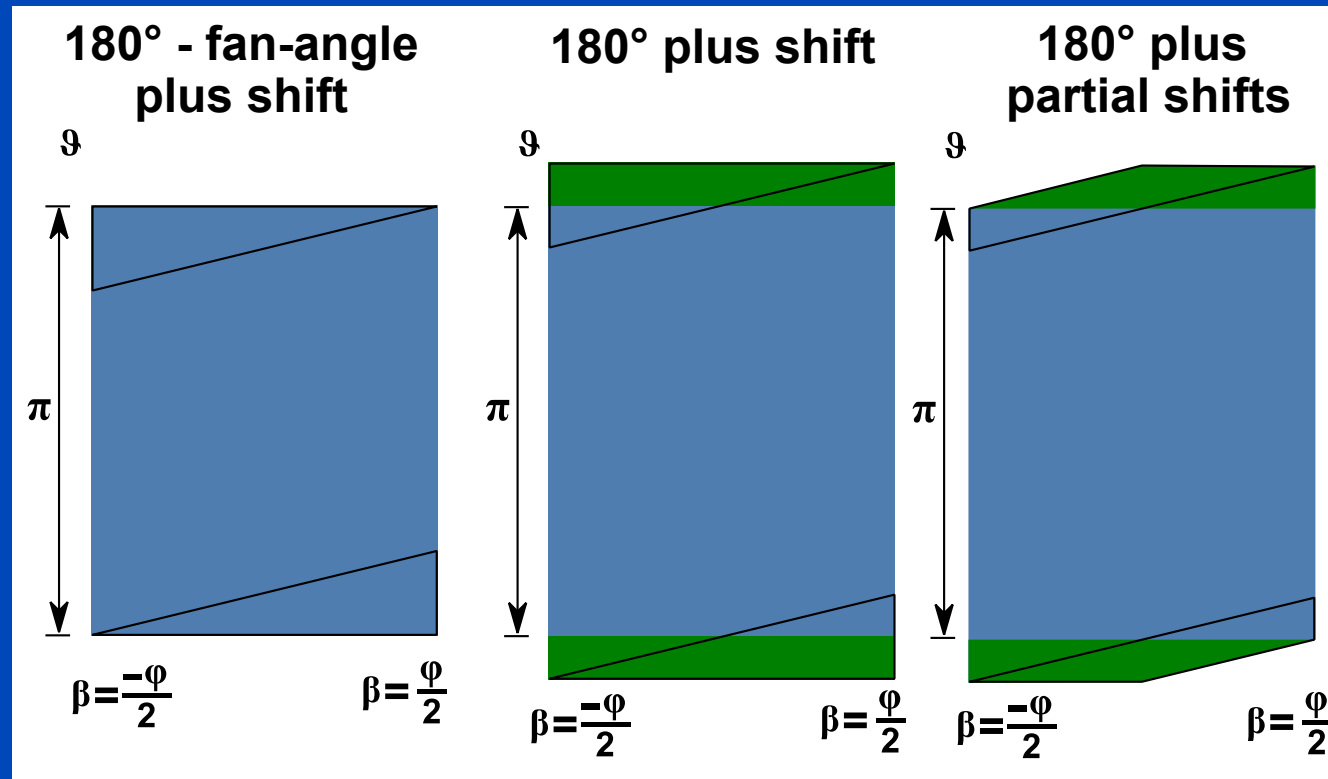
- Rotate-plus-shift sinogram with dynamic collimation





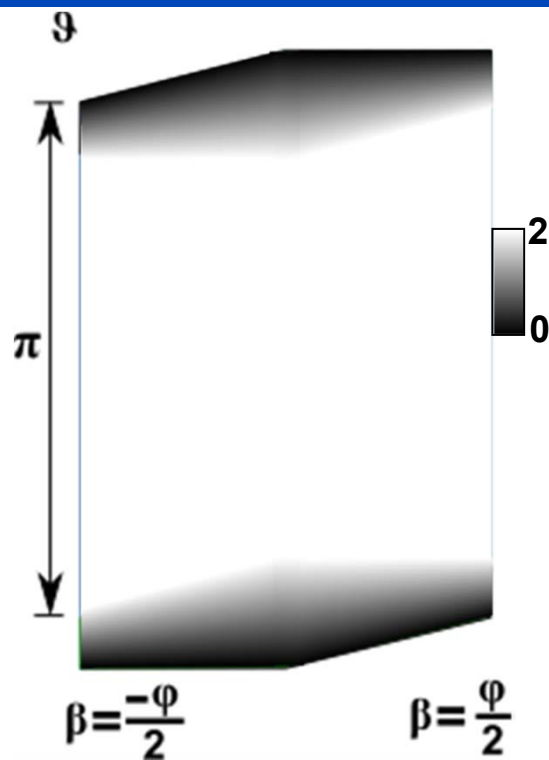
# Rotate-Plus-Shift Trajectory

- Any combination of rotation and shift complying with the completeness condition is possible.



# C-Arm System Design

- Data completeness condition leads to redundant data in circular short scans.



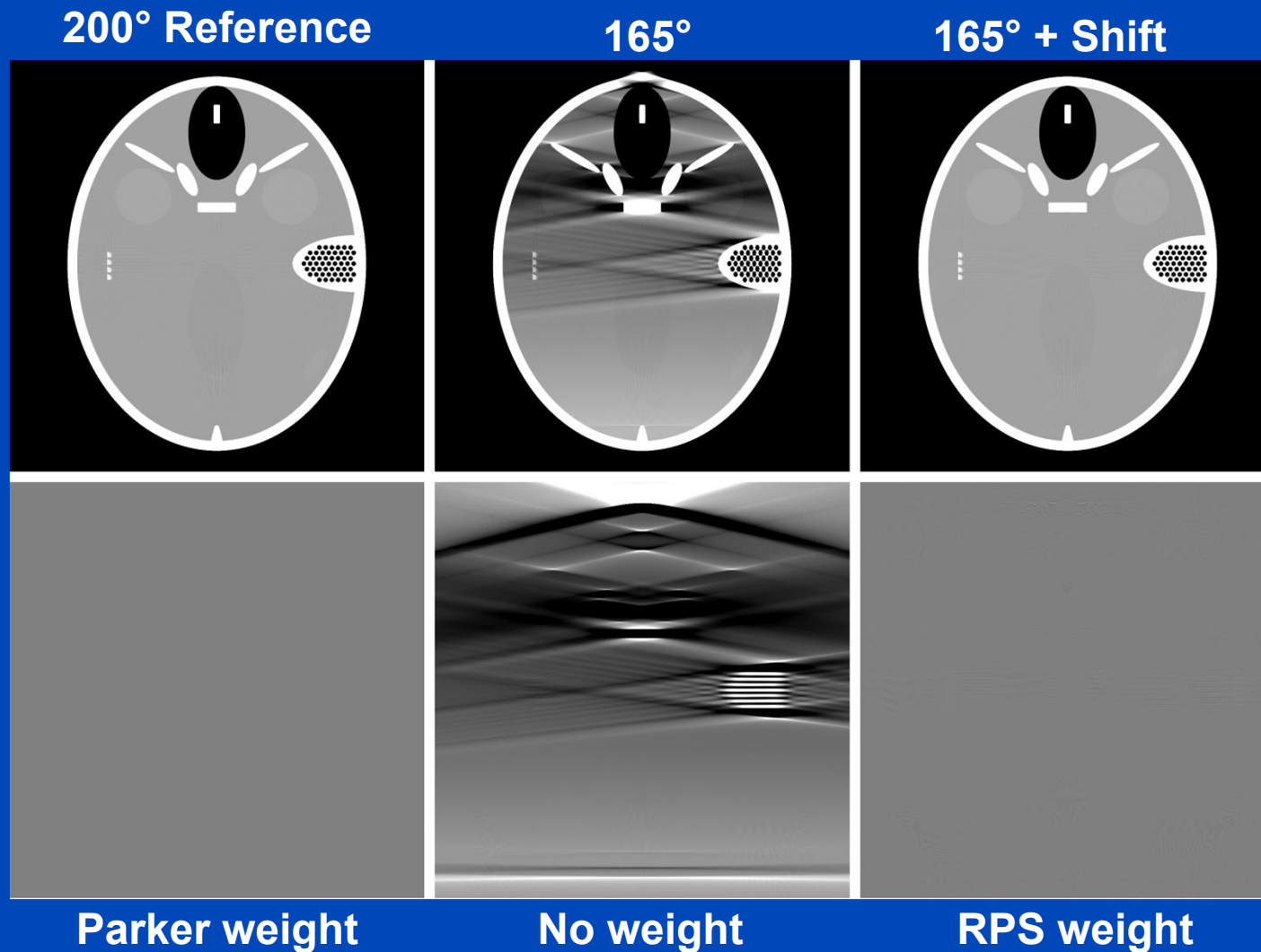
$g(\beta)$  :  $\beta$ - dependent angular range

$h(\beta)$  :  $\beta$ - dependent offset

**A generalization of the Parker weight leads to the RPS weight:**

$$w(\vartheta, \beta) = \begin{cases} 0 & \text{if } \vartheta < \alpha_1 + h(+\beta) - g(+\beta) \\ 1 + s\left(\frac{\vartheta - \alpha_1 - h(+\beta)}{g(+\beta)}\right) & \text{else if } \vartheta < \alpha_1 + h(+\beta) + g(+\beta) \\ 2 & \text{else if } \vartheta < \alpha_2 + h(-\beta) - g(-\beta) \\ 1 - s\left(\frac{\vartheta - \alpha_2 - h(-\beta)}{g(-\beta)}\right) & \text{else if } \vartheta < \alpha_2 + h(-\beta) + g(-\beta) \\ 0 & \text{else} \end{cases}$$

# Forbild Head Phantom

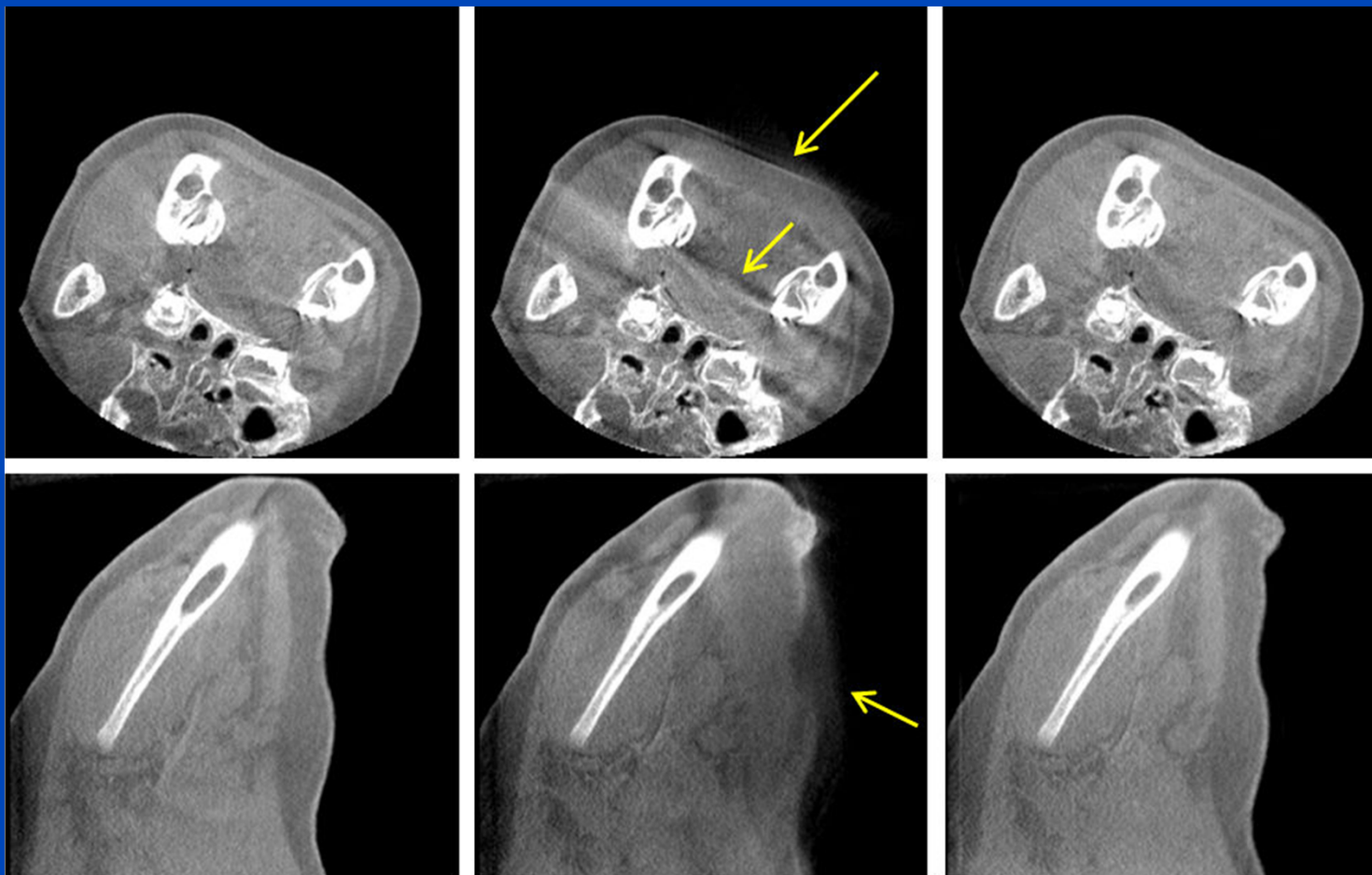


# In-vivo Measurements

200° Reference

165°

165° + Shift



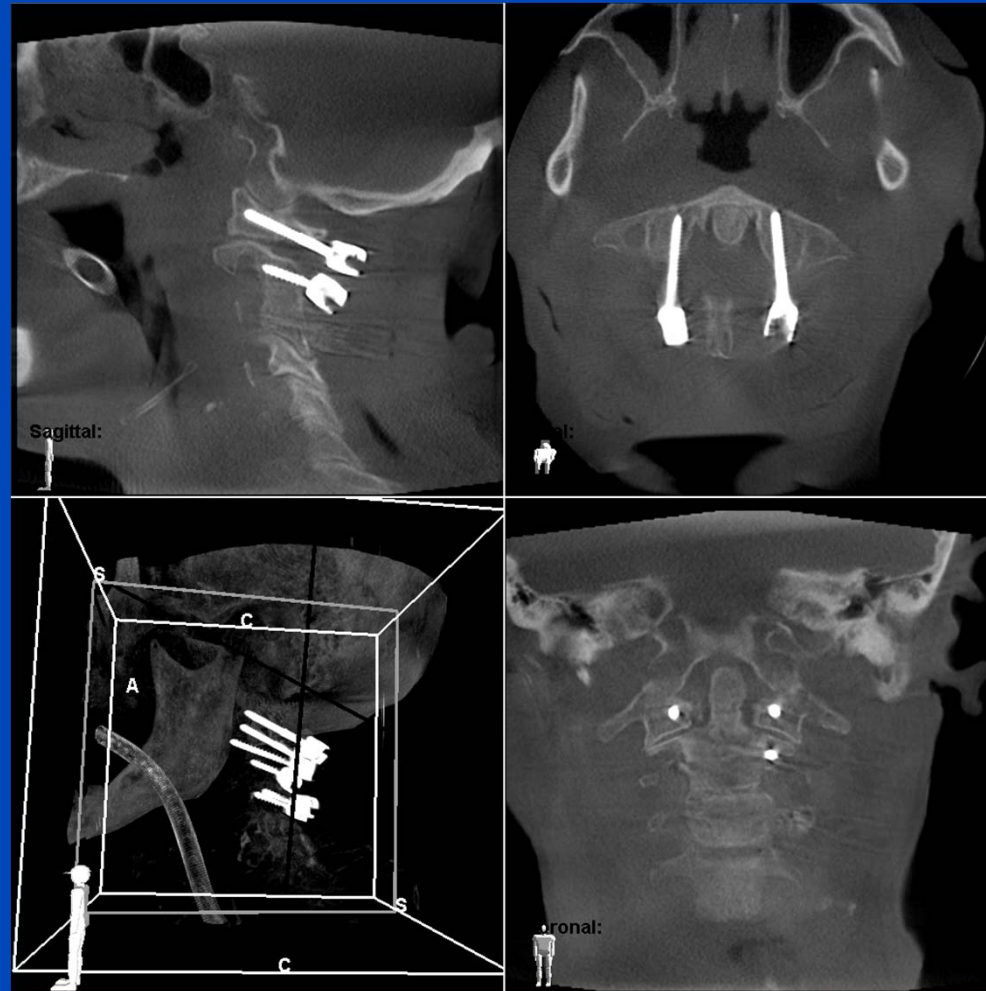
Parker weight

No weight

RPS weight

# First Clinical Case

- Cervical spine fixation (University of Leipzig, Germany)



# Conclusion

- The proposed weighting can be used for a wide range of non-conventional trajectories.
- Flexible and dose-efficient data acquisition can be used.
- Enables acquisition of full datasets with compact C-arm systems.

# Thank You!



The 4<sup>th</sup> International Conference on  
**Image Formation in X-Ray Computed Tomography**

July 18 – July 22, 2016, Bamberg, Germany  
[www.ct-meeting.org](http://www.ct-meeting.org)



Conference Chair

**Marc Kachelrieß**, German Cancer Research Center (DKFZ), Heidelberg, Germany

**This presentation will soon be available at [www.dkfz.de/ct](http://www.dkfz.de/ct).**  
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